

## ROMANIA Ministry of National Defence





# MILITARY TECHNICAL ACADEMY "FERDINAND I" Education and Scientific Research

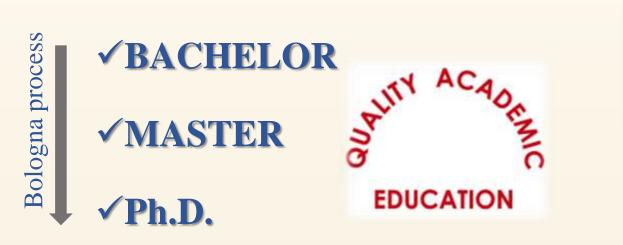
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# **TRAINING AREA**







# **✓POSTGRADUATE COURSES**





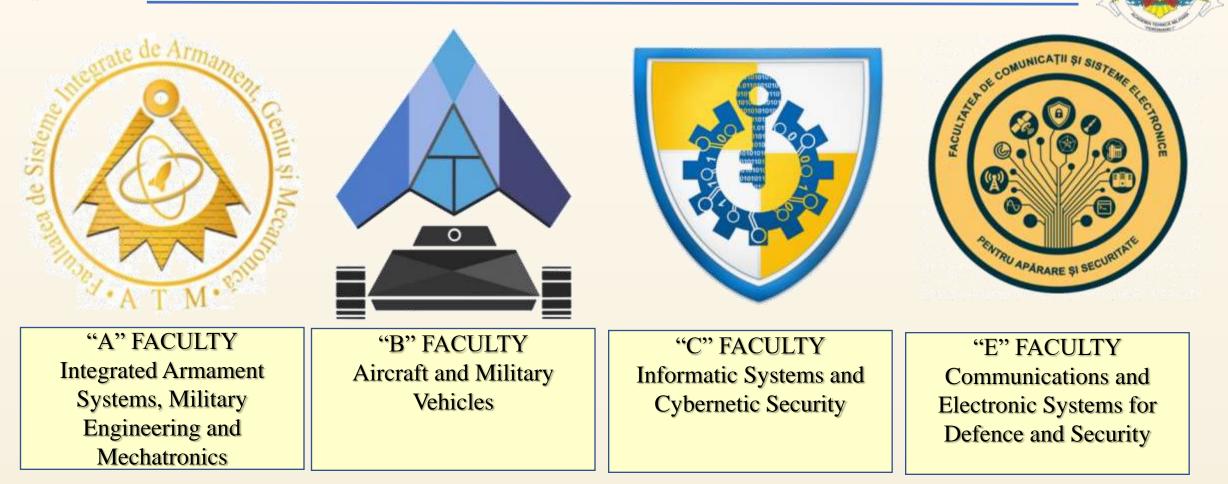












"D" DEPARTMENT Foreign Languages, Military Science and Management







### "A" FACULTY Integrated Armament Systems, Military Engineering and Mechatronics





"A1" DEPARTMENT Department of Armament Systems and Mechatronics

"A2" DEPARTMENT Department of Civil Engineering, Military Engineering and Geomatics

Centre of Excellence in Armament Integrated Systems, Military Engineering and Mechatronics (CESIAG)





#### **"B" FACULTY Aircraft and Military Vehicles**





"B1" DEPARTMENT Department of Military Vehicles and Transport

"B2" DEPARTMENT Department of Integrated Aircraft Systems and Mechanics

Centre of Excellence in Self-Propelled Systems and Technologies for Defence and Security (SATAS)





#### **"C" FACULTY** Informatic Systems and Cybernetic Security





"C1" DEPARTMENT Department of Computers and Cybernetic Security`

> "C2" DEPARTMENT Department of Applied Informatics

Centre of Excellence In Cyber Security Advanced Technologies (CETASC)





#### **"E" FACULTY Electronic Systems for Defence and Security**



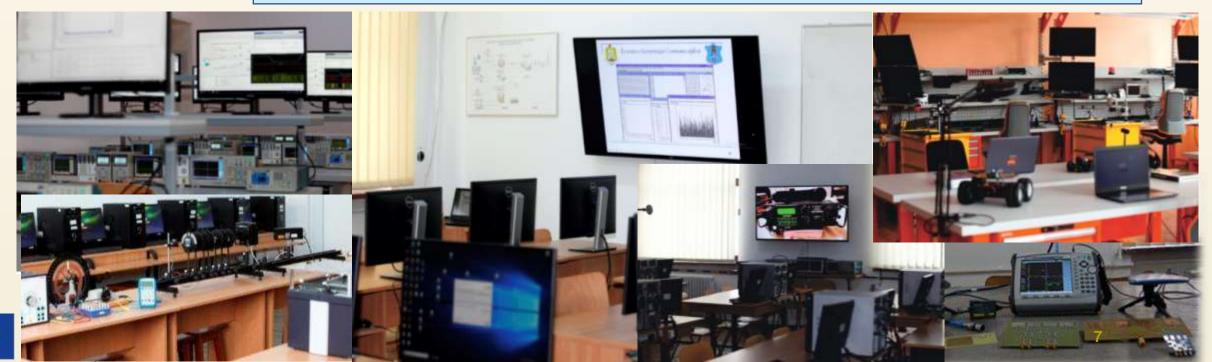


"E1" DEPARTMENT Department of Communications and Information Technology

#### "E2" DEPARTMENT

Department of Military Electronic Equipment and Information Technology

Centre of Excellence in Communications and Information Technology (CECTI) Centre of Excellence in Robotics and Autonomous Systems (CERAS)





### **"D" DEPARTAMENT** Foreign Languages, Military Science and Management





Didactic Commission of Foreign Languages and Intercultural Communication

> Didactic Commission of Tactics, Physical Education and Sport

Didactic Commission of Euro-Atlantic Security and Management





### **KA2 Project EUCTSDS**

### **European Common Technical Semester for Defence and Security**



No.	Subjects				
1	Applied Informatics	Network of teachers	RO MTA	RO MTA	3
2	Applied Automation for Engineering Systems	Network of teachers	PL MUT	KO WHA	3
3	Integrated Weapon Systems	Network of teachers	ROMIA	FR FASFA	3
4	CSDP for Technical Systems	Network of teachers	FR FASFA		3
<mark>5</mark> a	Computer Networks	Network of teachers	BG NMU	_	3
<u>6a</u>	Programming Languages	Network of teachers	RO MTA	BG NMU	3
7a	Signal Processing	Network of teachers	GR HAFA		3
<mark>8a</mark>	Microcontrollers	Network of teachers	RO MTA		3
5b	Propulsion Systems	Network of teachers	GR HAFA	_	3
6b	Dynamic of Flight	Network of teachers	PL MUT	PL MUT	3
7b	Mechanics and Material Science	Network of teachers	GR HAFA		3
8b	Computer-Aided-Design and Numerical Analysis	Network of teachers	BG NMU		3
9	Interdisciplinary Scientific Project			GR HAFA	6
10	Foreign Languages (Bulgarian/French/Greek/Polish/Romanian)				
11	Physical Education and Sports				2
TOTAL					34







# KA2 Project EUCTSDS

### **Basic Engineering Module**



LTTA – Basic Engineering + TPM RO MTA – Bucharest (18 – 24.04.2023)							
Sunday +Monday 16 + 17 April Orthodox Easter	Tuesday 18 <sup>th</sup> of April Arrival of Participants	Wednesday 19 <sup>th</sup> of April 1 <sup>st</sup> Day of LTTA Applied Informatics & Applied Automation for Engineering Systems	Thursday 20 <sup>th</sup> of April 2 <sup>nd</sup> Day of LTTA Intercultural communication CERC 2023 Traditional dinner	Friday 21 <sup>st</sup> of April 3 <sup>rd</sup> Day of LTTA Applied Informatics & Applied Automation for Engineering Systems	Saturday 22 <sup>nd</sup> of April 4 <sup>sth</sup> Day of LTTA Applied Informatics & Applied Automation for Engineering Systems	Sunday 23 <sup>rd</sup> of April 5 <sup>sth</sup> Day of LTTA Applied Informatics & Applied Automation for Engineering Systems	Monday 24 <sup>th</sup> of April 6 <sup>th</sup> Day of LTTA Applied Informatics & Applied Automation for Engineering Systems
			EuCTSd	ls TPM			



Co-funded by the Erasmus+ Programme of the European Union







- Applied Informatics
- The students learn the basics of programming using the engineering programming languages (ie Matlab).
- In this context, the basics of computer architecture including memory model and data types are also taught.
- ✓ After successful participation, the students are able to design algorithms and programmes, applied in Mechanical and Aerospace Engineering, Electronic Engineering or Computer Science.









### **Applied Automation of Engineering Systems**

#### **Goal of the Module:**

- Education, discovering and understanding practical principles of control systems and robotics.
- Learning about mathematical analysis of linear control systems, stability assessments, control quality, synthesis methods and correction of automation systems' dynamic properties.
- Learning about the mathematical description and analysis of robotics systems, structural and functional analysis.
- Discovering and understanding practical matters regarding control and robotics systems.

#### **Main Topics:**

- 1. Mathematical Models of Automation Systems. (Lec.: 2h; Exer.: 4h)
- 2. Design the Controller and Synthesis of the Automation Control Systems. (Lec.: 2h; Exer.: 4h)
- 3. Modelling, Control Design and Experiment of 2 DOF/3 DOF Helicopter. (Exer.: 2h, Lab:4)
- 4. Modelling, Control Design and Experiment of Inverted Pendulum/ Rotary Double Inverted Pendulum. (Exer.: 2h, Lab:4)
- 5. Introduction to manipulators and robot systems (construction and control). (Lec.: 2h, Lab.:4)
- 6. Environments for offline programming of robots. (Lec.: 2h; Lab.: 4h)
- 7. Selected online robot control systems. (Lec.: 2h; Lab.: 4h)

#### **Competences:**

- Students will learn about the construction of automation and robotic systems, modelling, simulation, programming languages, and work principles in the subject.
- Classes provide knowledge in the field of modelling robotic stations and programming robots.



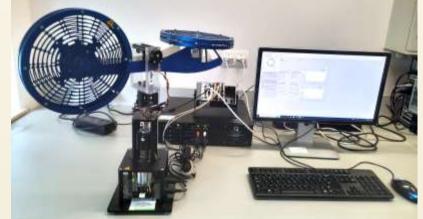


### **Applied Automation of Engineering Systems**

- **1. Mathematical Models of Automation Systems.** (*Lec.: 2h; Exer.: 4h*), Creating of linear models of control systems as transfer-function model, frequency model, state-space model, time and frequency characteristics, characteristics of fundamental dynamic elements, block diagrams. The goal of the classes is to model, design and simulation of some control system in Matlab software.
- **2. Design the Controller and Synthesis of the Automation Control Systems.** (*Lec.: 2h; Exer.: 4h*)

The types, characteristics and parameters of the classical controllers. Ziegler-Nichols controller design method. Root locus design method. The goal of the classes is to model, design, and simulate some control system in Matlab software.







Co-funded by the Erasmus+ Programme of the European Union 3. Modelling, Control Design and Experiment of 2 DOF/3 DOF Helicopter (*Exer.: 2h*, *Lab:4*),

The objective of this classes is to model, design and test the helicopter model mounted on a fixed base with two propellers driven by DC motors. The front propeller controls the elevation of the helicopter nose about the pitch axis, and the back propeller controls the side-to-side motions of the helicopter about the yaw axis. The pitch and yaw angles are measured using high-resolution encoders. The pitch encoder and motor signals are transmitted via a slipring.







### **Applied Automation of Engineering Systems**

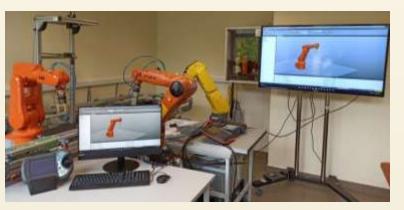
#### 4. Modelling, Control Design and Experiment of Inverted Pendulum/ Rotary Double Inverted Pendulum (Exer.: 2h, Lab.:4)

The objective of this classes is to design and implement a state-feedback control system that will balance the pendulum in the upright, vertical position / will balance a rotary double inverted pendulum and positions the rotary arm to a commanded angular position.

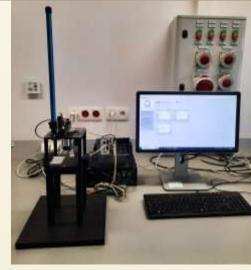
**5. Introduction to manipulators and robot systems (construction and control).** (*Lec.: 2h, Lab.:4*),

Presentation of the construction of selected types of manipulators, controllers and control panels. Configuration of the robot system. Presentation of the robot control methodology.













**Applied Automation of Engineering Systems** 

# **5. Introduction to manipulators and robot systems (construction and control).** (*Lec.: 2h, Lab.:4*),

Presentation of the construction of selected types of manipulators, controllers and control panels. Configuration of the robot system. Presentation of the robot control methodology.

#### **6. Environments for offline programming of robots.** (*Lec.: 2h; Lab.: 4h*)

Overview of selected environments for offline programming of robots. Acquainting with the methodology of offline robot programming. Configuration of the robot system in offline mode. Programming the manipulator movement for a selected task in a virtual environment. Conducting a simulation and analysis of the implemented process.

#### **7. Selected online robot control systems.** (*Lec.: 2h; Lab.: 4h*)

Overview of selected online robot control systems. Acquainting with the methodology of online robot programming. Configuration of the robot system in online mode. Programming the manipulator movement for a selected task in a real environment. Running a real robot and analysing the process being carried out.











### KA2 Project EUCTSDS Basic Engineering Module





Applied Informatics Applied Automation for Engineering Systems





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### **KA2 Project EUCTSDS**

### **European Common Technical Semester for Defence and Security**



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	TOTAL				





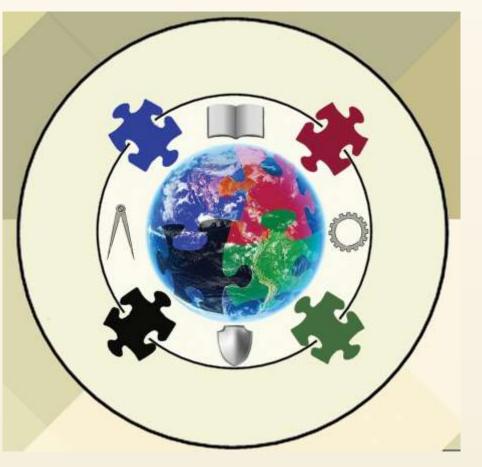


**European Common Technical Semester for Defence and Security** 

# SUPPLEMENTARY SUBJECTS INTERCULTURAL COMMUNICATION



- Foundations of intercultural communication
- Characteristics of host country language
- Host country cultural landmarks
- Culture, communication, context and power
- Identity, stereotypes, prejudices and labels
- Verbal and nonverbal codes











- The role of intercultural communication is to make it easier for us to relate to people who belong to different cultures, who speak a different language and have a different nationality and different identity references, in order to better understand our own culture and specificity, and ultimately ourselves.
- https://www.istockphoto.com/ro/ilustra%C8%9B ii/intercultural-communication
- The study of intercultural communication begins like a *journey into another culture*, and ends up becoming a foray into one's own culture and identity.
- Meeting with **the Other**, **the alterity**, gives you the opportunity to get to *know yourself better*, by **comparison**.
- Faced with new and diverse contexts and situations, you can only respond appropriately if you *have fully understood* and discovered who you really are, not who you think you are or who you would like to be.

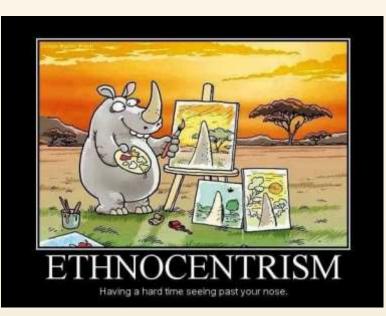








There are also barriers to effective intercultural communication, such as: stereotypes, prejudice, discrimination, labelling, etc., which occur *in diverse and complex historical, social and political contexts*.



https://mobile.twitter.com/hashtag/etnocentrism?src=hash



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• Another impediment is **ethnocentrism**, or the tendency to consider our own culture superior to other cultures.

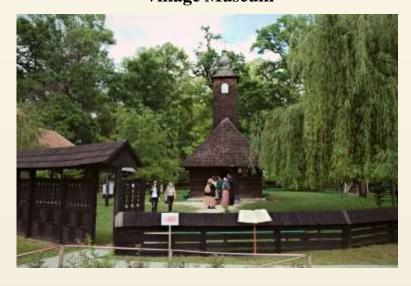






- When we talk about intercultural communication, we implicitly refer to **culture** as a central concept in defining and describing our interactions.
- **Culture** has various definitions, including that it *describes a particular combination of perceptions that influence communication*.
- Therefore, patterns of behaviour and attitudes that are common to groups of people define culture.
  Romanian Athenaeum
  Village Museum











### **European Common Technical Semester for Defence and Security**

## SUPPLEMENTARY SUBJECTS INTERCULTURAL COMMUNICATION



- are a set of deeply held beliefs that a group shares and *identifies with*;
- are patterns, systems of symbols and rules handed down from generation to generation;
- are socially and historically determined;
- reflect a common idea and perception of how things should be.
- **Culture** is a network of symbols with contextual meaning.



- Keywords :
- culture and civilization;
- common language;
- values, principles;
- social norms;
- education;
- family structures;
- history;
- religion;
- beliefs;
- traditions, customs;
- myths and folklore.









- Intercultural communication operates massively with similarities and differences between cultures.
- Keyword: **IDENTITY**
- personal,
- family,
- religious,
- spiritual identity,
- *identity related to age,*
- race,
- *sex*,
- gender,
- sexual orientation,
- belonging to a majority or minority, etc.



- Other **factors shaping intercultural communication** are:
- language spoken;
- *context* (social, political, historical, emotional, psychological);
- *discourse* in context;
- *poles of power* based on social hierarchies that privilege certain groups and categories based on:
  - stable factors (age, ethnicity, race, sex, sexual
- orientation, gender, physical abilities);
  - variable factors (education, culture,
- geographical area, marital status, socio-economic status).











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